## Structure verification and validation

# **Protein Structure Analysis**

Iosif Vaisman

2023

Anolea Verify3D Procheck WhatIf

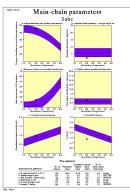
# Bond lengths (Procheck)

Bond	labeling		Value   sigma
C-N	C-NH1   C-N	(except Pro)   (Pro)	1.329   0.014
C-O	C-0	i	1.231   0.020
Calpha-C	CH1E-C   CH2G*-C	(except Gly)	1.525   0.021   1.516   0.018
Calpha-Cbeta	CH1E-CH3E   CH1E-CH1E   CH1E-CH2E	(Ala) (Ile,Thr,Val) (the rest)	1.521   0.033   1.540   0.027   1.530   0.020
N-Calpha	NH1-CH1E   NH1-CH2G*   N-CH1E	(except Gly,Pro)   (Gly)   (Pro)	1.458   0.019   1.451   0.016   1.466   0.015

# Bond angles (Procheck)

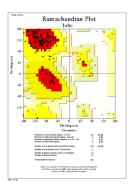
Angle	labeling		Value   sigma
C-N-Calpha	C-NH1-CH1E	(except Gly,Pro)	121.7   1.8
	C-NH1-CH2G*	(Gly)	120.6   1.7
	C-N-CH1E	(Pro)	122.6   5.0
Calpha-C-N	CH1E-C-NH1	(except Gly,Pro)	116.2   2.0
	CH2G*-C-NH1	(Gly)	116.4   2.1
	CH1E-C-N	(Pro)	116.9   1.5
Calpha-C-O	CH1E-C-O   CH2G*-C-O	   (except Gly)   (Gly)	120.8   1.7   120.8   2.1

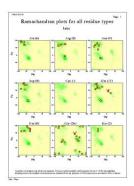
# Procheck output



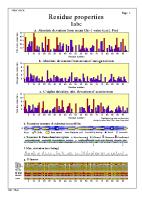
- a. Ramachandran plot quality percentage of the protein's residues that are in the core regions of the Ramachandran plot.
- b. Peptide bond planarity standard deviation of the protein structure's omega torsion angles
- c. Bad non-bonded interactions number of bad contacts per 100 residues.
- d.  $C\alpha$  tetrahedral distortion standard deviation of the  $\zeta$  torsion angle ( $C\alpha$ , N, C, and  $C\beta$ ).
- e. Main-chain hydrogen bond energy standard deviation of the hydrogen bond energies for main-chain hydrogen bonds.
- **f. Overall G-factor** average of different G-factors for each residue in the structure.

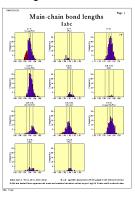
# Procheck output





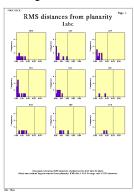
# Procheck output



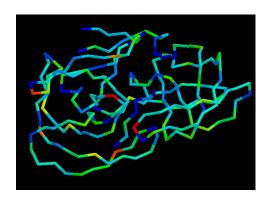


# Procheck output

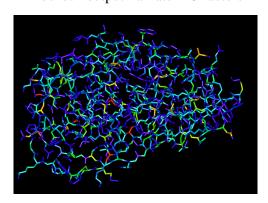




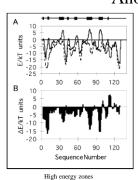
## Procheck output - backbone G factors

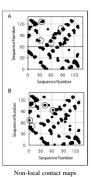


# Procheck output - all atom G factors



# Anolea

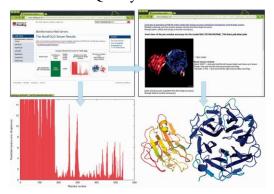




Non-local contact maps

Melo et al., 1997

# Model Quality Assessment



L.J.McGuffin et al., 2013

# Local structure comparison algorithms

# Protein Local Structural Comparison problem Pattern Matching ASSAM, Artymiuk et al., JMB'94 Pair-wise comparison Pints, Russell, JMB'98 Pints, Russell, JMB'98 Protein Local Structural Pattern Discovery Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery Sequence-dependent TRILOGY, Bradley et al. RECOMB'01 Protein Local Structural Pattern Discovery

Huan, 200

# Root mean square deviation

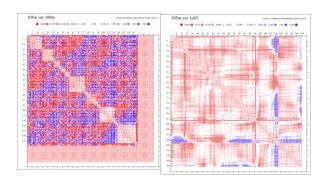
### Coordinate based RMSD

$$RMSd(A, B) = \min_{T} \sqrt{\sum_{i=1}^{m} (A_i - TB_i)^2}$$

### Distance based RMSD

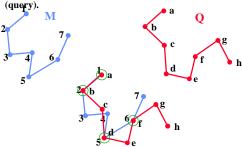
$$RMSd_D(A, B) = \frac{1}{m} \sqrt{\sum_{i=1}^{m} \sum_{j=1}^{m} (d_{ij}^A - d_{ij}^B)^2}$$

### Difference Distance Matrix Plot (DDMP)



# Geometric Hashing

Find common subsets, invariant under rotation and translation in two point sets M (model) and Q (query)



Finding the maximum coincidence set is an NP-hard problem

# Geometric Hashing Reference frames

- $\bullet \ Two \ points \ (basis \ pair) \ define \ a \ reference \ frame$
- The coordinates of all points are computed in the reference frame (reference frame system)
- There will be pairs of points (from M and Q) with the same coordinates
- The number of such pairs depends on selection of reference frame and reference frame system resolution

# Geometric Hashing Algorithm

### **Preprocessing**

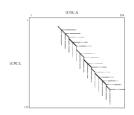
Hash table H is created. It has a bin for each cell in the frame systems. The coordinates of all points in each model frame system are calculated. If there is a point in the cell (p,q) in the frame system with basis  $(a_i,a_k)$ , then  $(a_i,a_k)$  is placed in the bin H(p,q)

### Recognition

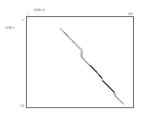
A pair of points in the query is chosen as basis, and the coordinates of the other points are calculated. These coordinates are used as indices for H, and for each cell being indexed, a vote is given for the (model) basis pairs in the cell. The number of votes for a model basis pair is the number of coinciding points to the query (using the specified query basis pair)

### Combinatorial Extension (CE) Algorithm

### Structure alignment of phycocyanin (1CPC:L) to colicin A (1COL:A)

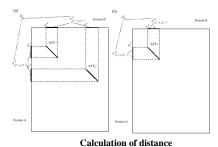


The solid line represents the optimal path built from AFPs. The dotted line represents the search area at every step of path extension.



The thick solid line represents alignment overlap both before and after optimization.

### Combinatorial Extension (CE) Algorithm



Dij for two AFPs i and j from the path Dii for single AFP i from the path.

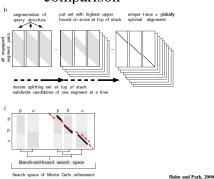
# TO ANY THE STATE OF THE STATE O

MRCCAZ (LECTAS (LECTAS (LECTAS) CASE ALL (1.5 / 2 - 10 - 1 - 1 ) (1.5 / 2 - 10 - 1 ) (

### jCE and jFATCAT tool at RCSB

Pairwise structure alignment and pre-calculated 3D structure comparisons for the entire PDB

# DaliLight algorithm for protein structure comparison



# Search for common substructures by clique detection

Prlić et al., 2010

